

Validated Numerics for Algebraic Path Tracking

Alexandre Guillemot, Pierre Lairez

March 8, 2024

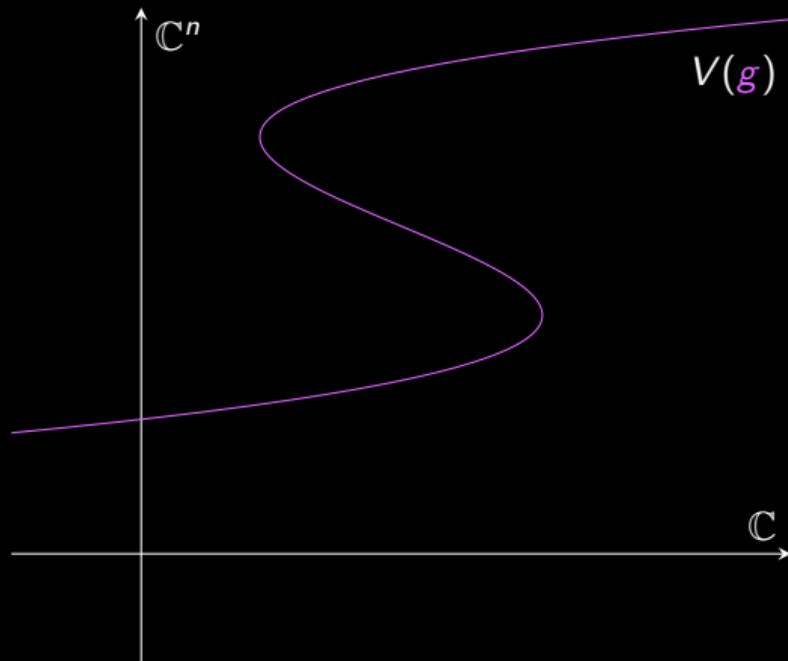
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Introduction

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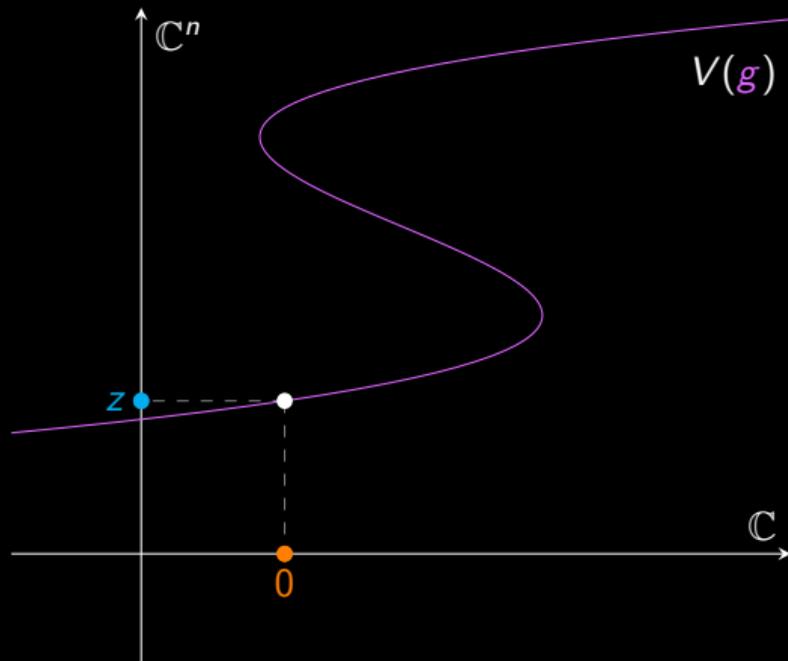
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- Notation : $g_t : \mathbb{C}^n \rightarrow \mathbb{C}^n$ defined by $g_t(z) = g(t, z)$.



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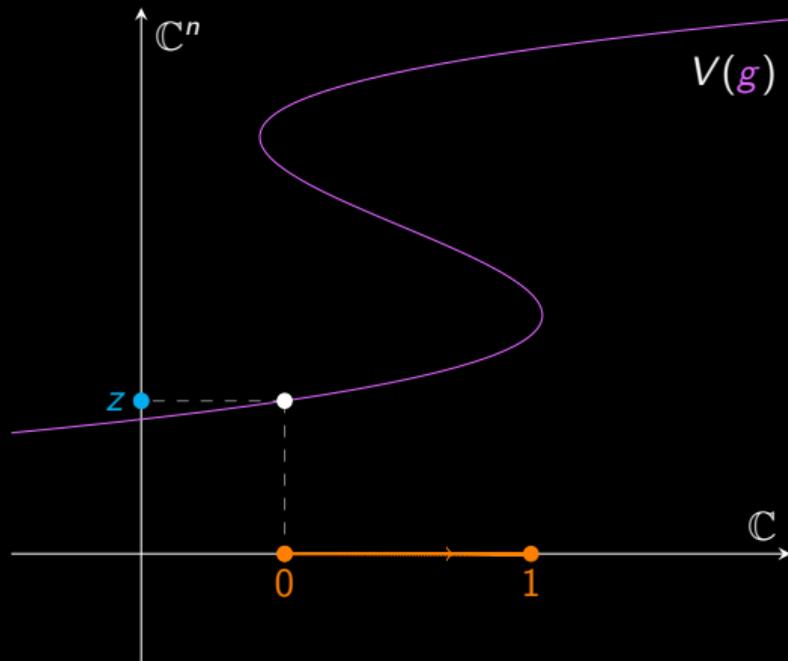
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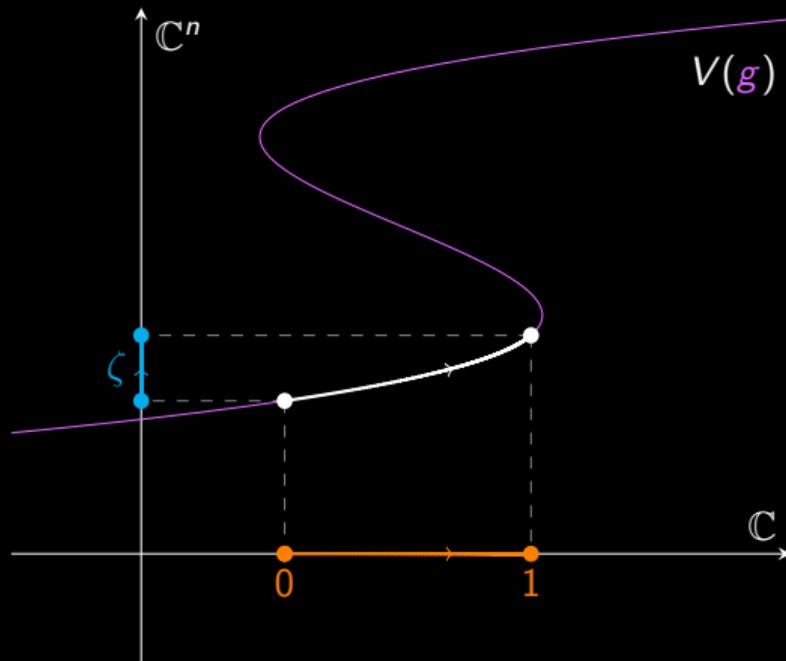
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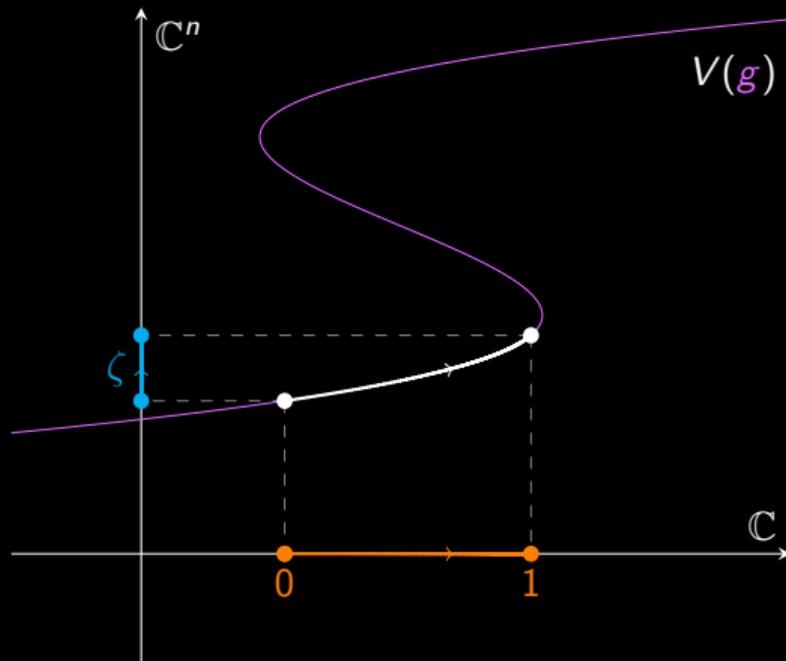
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- \Rightarrow Moving the parameter from 0 to 1 induces $\zeta : [0, 1] \rightarrow \mathbb{C}^n$ s.t. $\zeta(0) = z$ and $g_t(\zeta(t)) = 0$.



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- \Rightarrow Moving the parameter from 0 to 1 induces $\zeta : [0, 1] \rightarrow \mathbb{C}^n$ s.t. $\zeta(0) = z$ and $g_t(\zeta(t)) = 0$.
- Goal : “Track” ζ , with some topological guarantees.



To solve multivariate square polynomial systems

- State of the art method,
- **Only need guarantees on the endpoints** when tracking homotopies,
- Possible to use a non certified tracker and to certify *a posteriori* the endpoints,
- Efficient implementations of non-certified trackers : **HomotopyContinuation.jl**, **PHCpack**, **Bertini**, ...

Motivations

To solve multivariate square polynomial systems

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Effective algebraic topology

- **The certification of the whole path** is required,
- Many theoretical works, but only one implementation in **Macaulay2**,
- There is a huge gap between non-certified and certified methods in terms of the number of steps required to track a root,
- Goal : narrow this gap. Tools : **Interval arithmetic**, **Krawczyk's method**, **predictor**.

Path certification

Root isolation criterion (Krawczyk, Moore, Rump)

- $f : \mathbb{C}^n \rightarrow \mathbb{C}^n$ polynomial,
- $z \in \mathbb{C}^n$, $r \in \mathbb{R}_{>0}$, $A \in \mathbb{C}^{n \times n}$,
- $\rho \in (0, 1)$,

such that for all $u, v \in B_r$,

$$-Af(z) + [I_n - A \cdot Jf(z + u)]v \in B_{\rho r}.$$

Then there exists a unique $\tilde{z} \in z + B_{\rho r}$ s.t. $f(\tilde{z}) = 0$.

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Proof sketch

We show that $\varphi : z + B_{\rho r} \rightarrow \mathbb{C}^n$ defined by $\varphi(z) = z - Af(z)$ is a ρ -contraction map with values in $z + B_{\rho r}$.

Moore boxes

Let $f : \mathbb{C}^n \rightarrow \mathbb{C}^n$ be polynomial map and $\rho \in (0, 1)$.

Moore boxes

A ρ -Moore box for f is a triple (z, r, A) satisfying

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Problem

How do we check that a triple (z, r, A) is a Moore box on a computer ?

Interval arithmetic

We choose a set $\mathbb{F} \subset \mathbb{R}$ of representable numbers.

Interval space

- $\square\mathbb{R} = \{[a, b] \subseteq \mathbb{R} \mid a \leq b, a, b \in \mathbb{F}\}$,
- $\square\mathbb{C}$: pairs of elements of $\square\mathbb{R}$,
- $\square\mathbb{R}^n$ resp. $\square\mathbb{C}^n$: vectors of boxes in \mathbb{R} resp. \mathbb{C} of size n .

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Interval extension

Let $f : \mathbb{C}^n \rightarrow \mathbb{C}^m$. An *interval extension* of f is a map $\square f : \square\mathbb{C}^n \rightarrow \square\mathbb{C}^m$ such that

$$\forall Z \in \square\mathbb{C}^n, f(Z) \subseteq \square f(Z).$$

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Interval arithmetic gives an effective way to build an extension $\square f$ given a (polynomial) map f .

Interval certification of a Moore box

Algorithm

```
1 def  $M(\square f, \square Jf, z, r, A, \rho)$ :  
2   if  $-A \cdot \square f(z) + [I_n - A \cdot \square Jf(z + B_r)]B_r \subseteq B_{\rho r}$ :  
3     return True  
4   else:  
5     return False
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Proposition

If $\square f$ is an extension of f , $\square Jf$ is an extension of Jf and $M(\square f, \square Jf, z, r, A, \rho)$ returns True, then (z, r, A) is a ρ -Moore box for f .

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Proof

Fundamental property of interval arithmetic !

Algorithm

General idea

Input

- A polynomial map $g : \mathbb{C} \times \mathbb{C}^n \rightarrow \mathbb{C}^n$,
- A zero \tilde{z} of g_0 (represented by a $\frac{7}{8}$ -Moore box (z, r, A)).

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Moore boxes (z_t, r_t, A_t) for g_t isolating $\zeta(t)$, this for all $t \in [0, 1]$.

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Output

Moore boxes (z_t, r_t, A_t) for g_t isolating $\zeta(t)$, this for all $t \in [0, 1]$.

Output in practice

- Subintervals I_1, \dots, I_k covering $[0, 1]$,
- triples $(z_1, r_1, A_1), \dots, (z_k, r_k, A_k)$

such that (z_i, r_i, A_i) is a $\frac{7}{8}$ -Moore box for g on I_i .

Refine

input : $f : \mathbb{C}^n \rightarrow \mathbb{C}^n$; (z, r, A) a $\frac{7}{8}$ -Moore box

output : a $\frac{1}{8}$ -Moore box with same associated zero as (z, r, A)

algorithm : A balance between pseudo-Newton iterations and reducing r

Subroutines

Refine

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Thicken

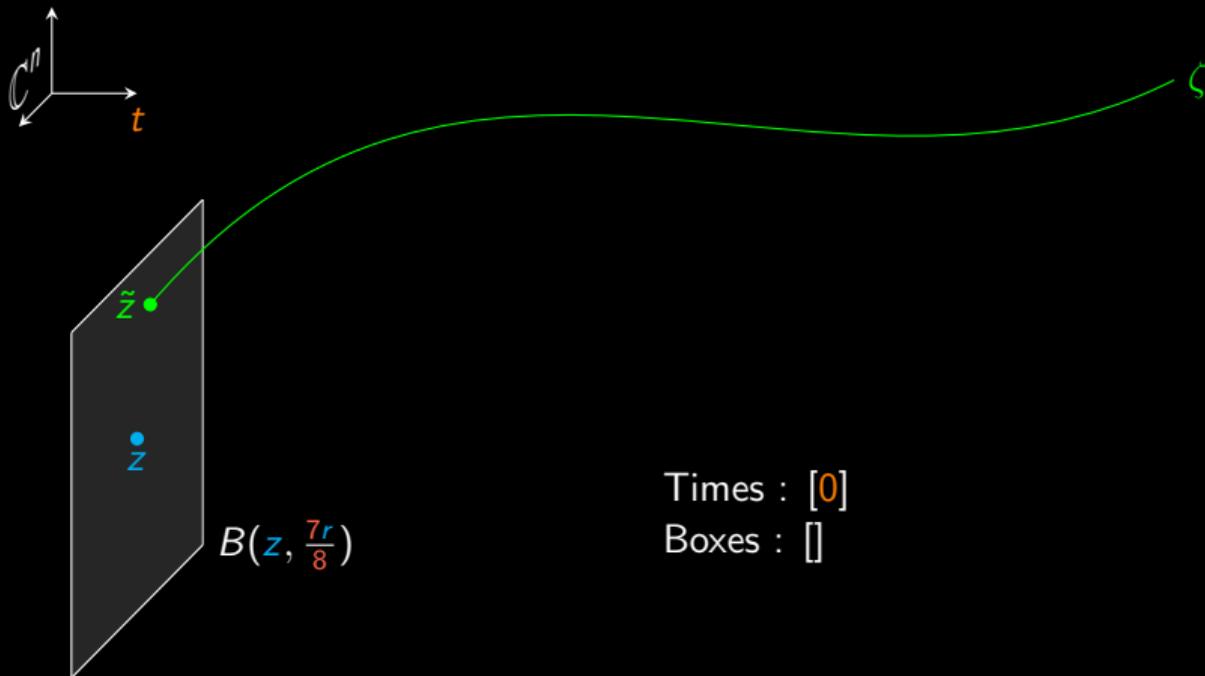
input : $g : \mathbb{C} \times \mathbb{C}^n \rightarrow \mathbb{C}^n$; $t \in [0, 1]$; (z, r, A) a $\frac{7}{8}$ -Moore box for g_t

output : $t' \in [0, 1]$ s.t. for all $s \in [t, t']$, (z, r, A) is a $\frac{7}{8}$ -Moore box for g_s

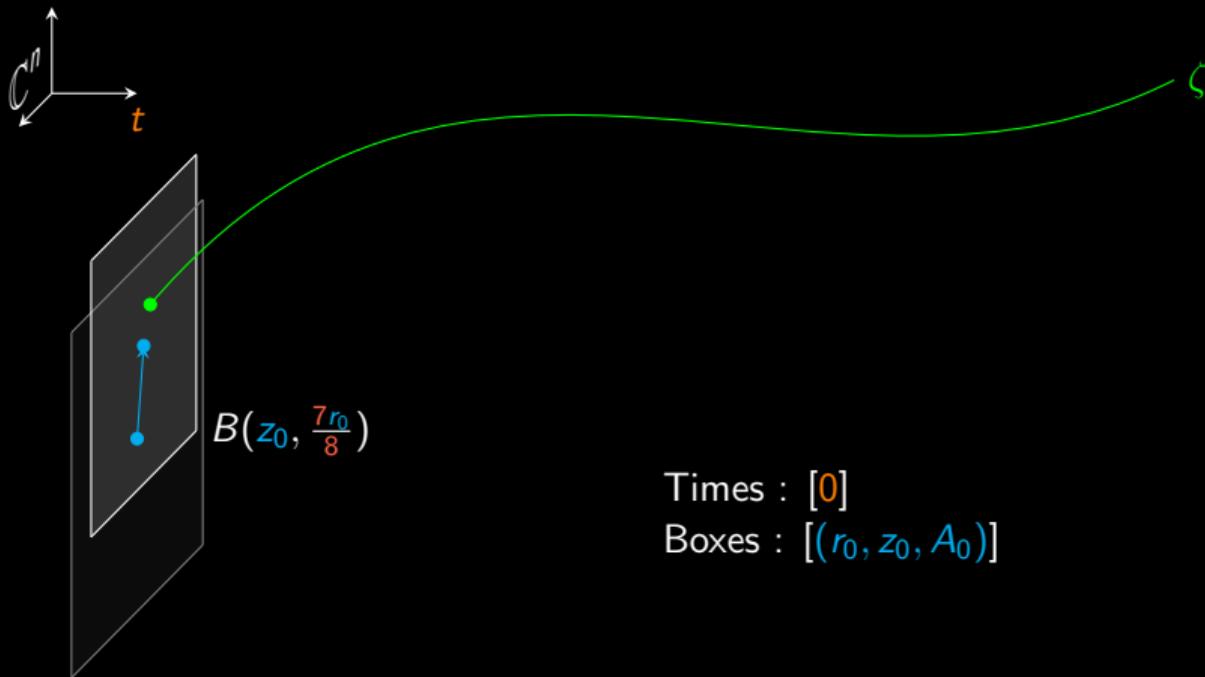
algorithm : Decrease t' until $M(\square g_T, \square Jg_T, z, r, A, \rho)$ returns True, where

- $T = [t, t']$,
- $\square g_T : \square \mathbb{C}^n \rightarrow \square \mathbb{C}^n$ is an extension of g_s for all $s \in T$,
- $\square Jg_T : \square \mathbb{C}^n \rightarrow \square \mathbb{C}^{n \times n}$ is an extension of Jg_s for all $s \in T$.

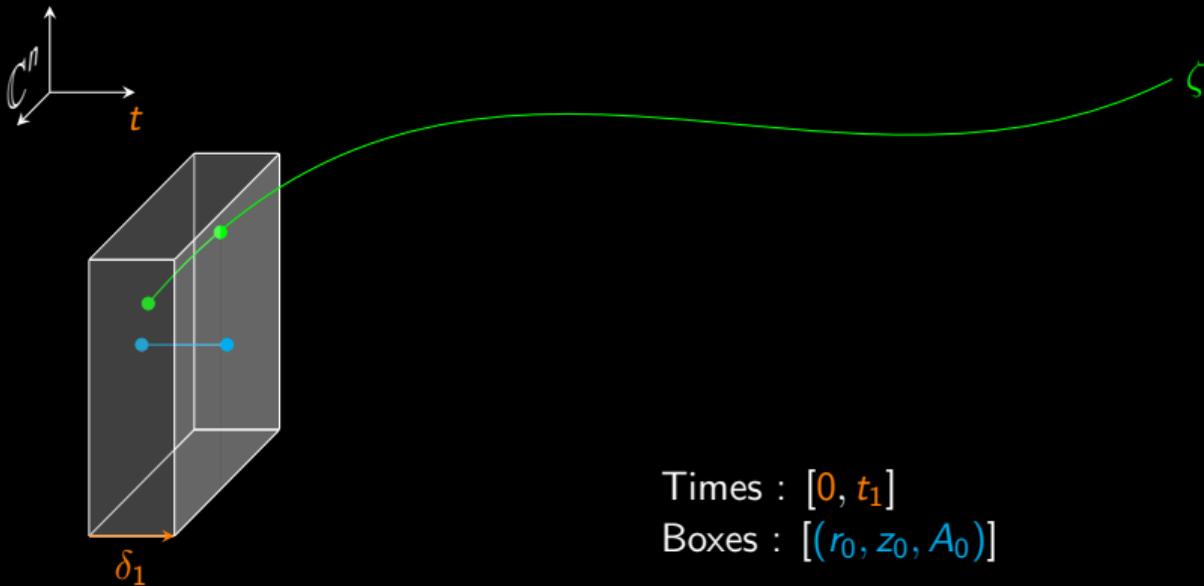
Flow of the algorithm



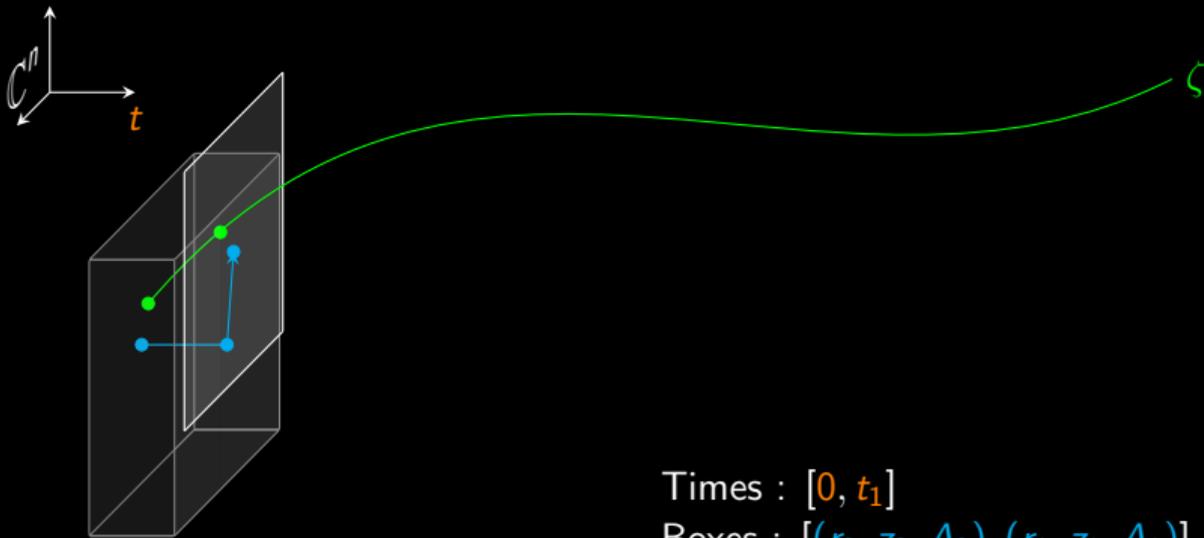
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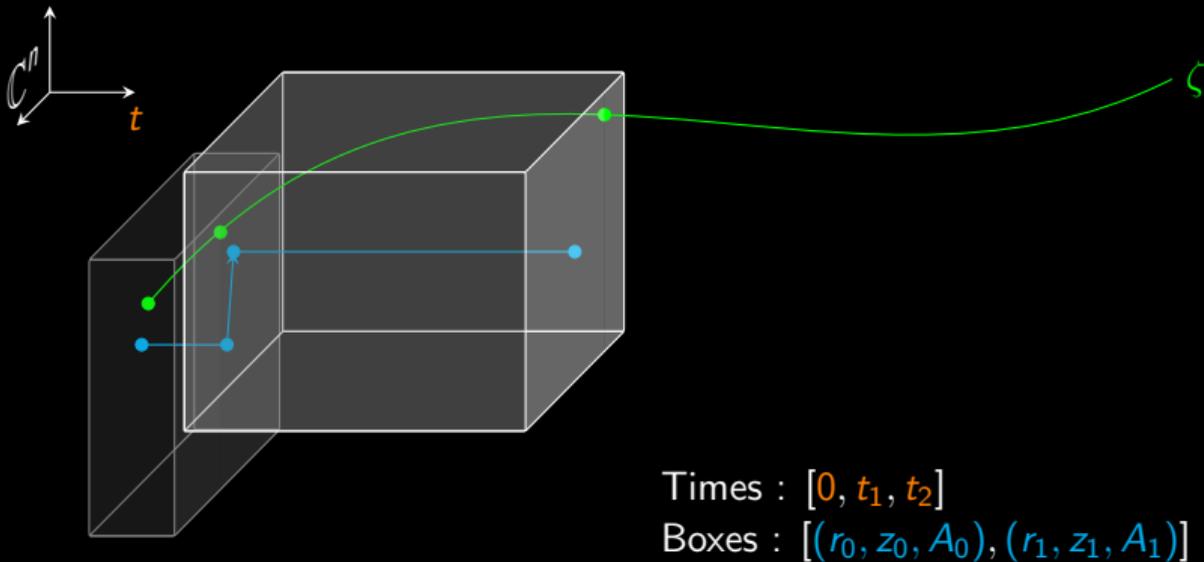
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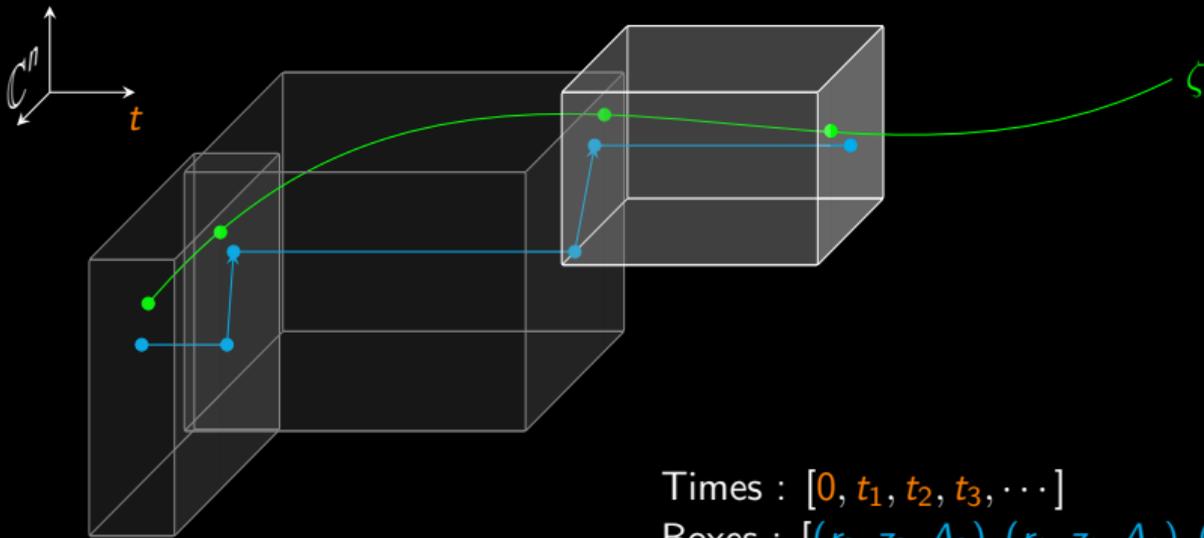
Times : $[0, t_1]$

Boxes : $[(r_0, z_0, A_0), (r_1, z_1, A_1)]$

Flow of the algorithm



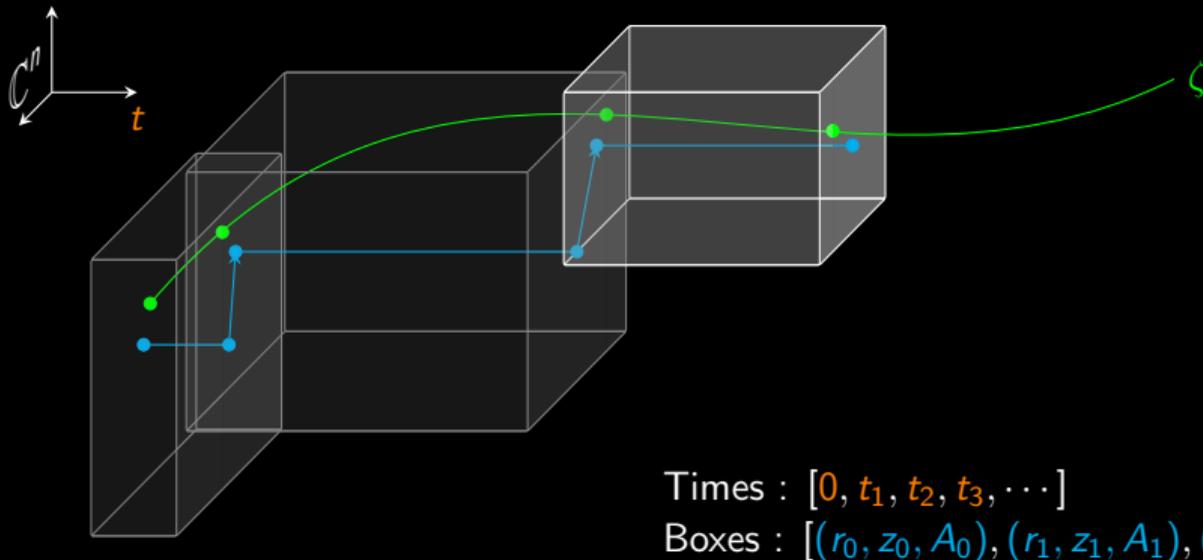
Flow of the algorithm



Times : $[0, t_1, t_2, t_3, \dots]$

Boxes : $[(r_0, z_0, A_0), (r_1, z_1, A_1), (r_2, z_2, A_2), \dots]$

Flow of the algorithm



Theorem (Guillemot, Lairez)

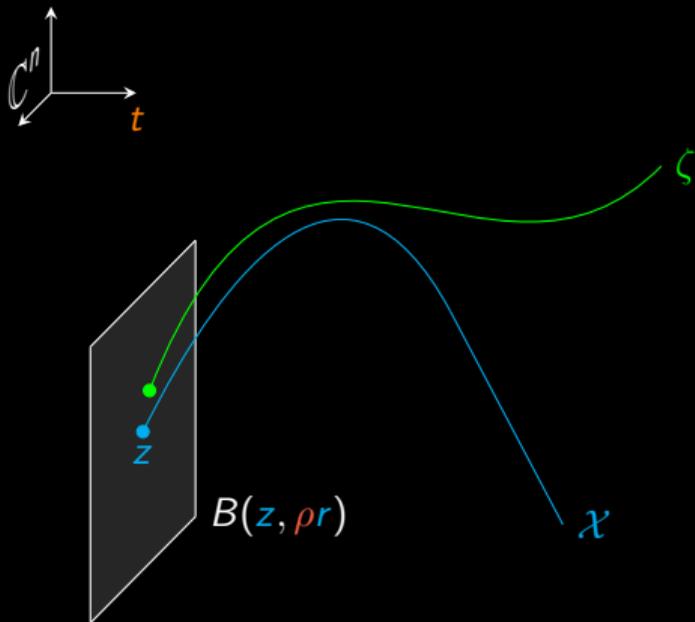
In a computation model with dynamic floating-point precision, the algorithm is correct and terminates.

Thickening with a predictor

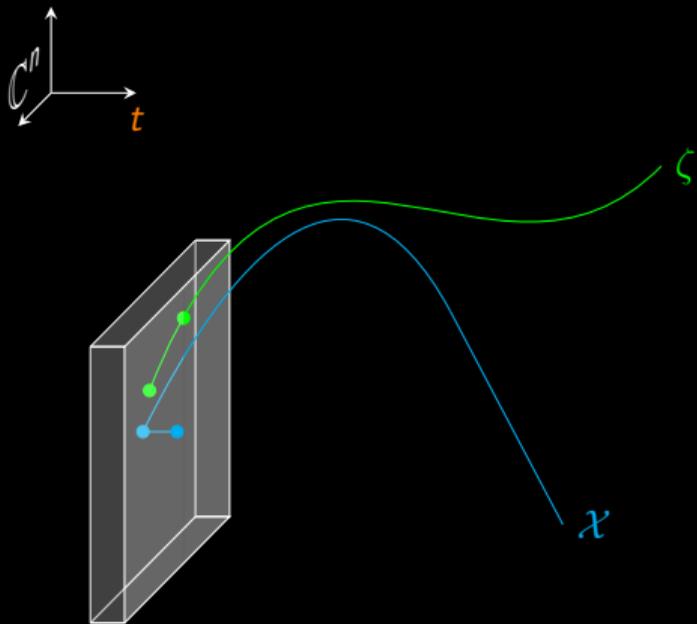
Predictor

A map $\mathcal{X} : \mathbb{R} \rightarrow \mathbb{C}^n$ such that $\mathcal{X}(t) = z$.

\mathcal{X} should stay close to ζ around t .



Thickening with a predictor



Predictor

A map $\chi : \mathbb{R} \rightarrow \mathbb{C}^n$ such that $\chi(t) = z$.

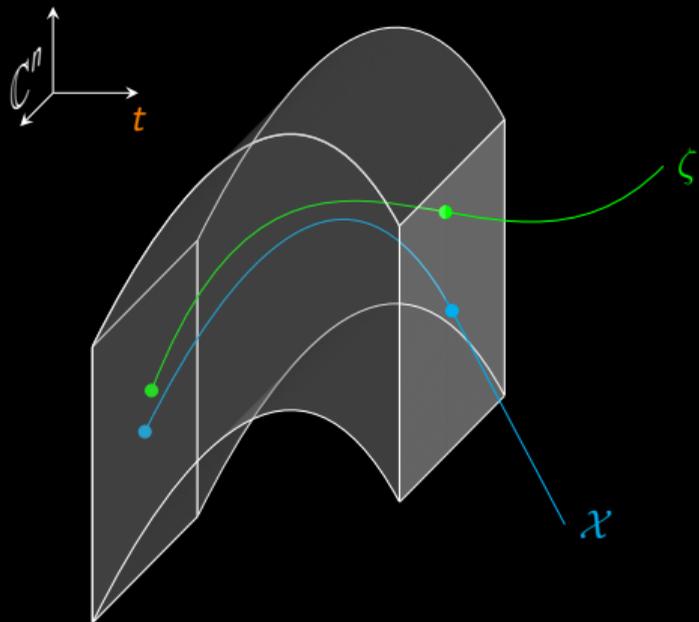
χ should stay close to ζ around t .

Certifying the prediction

Problem : check that for all $s \in [t, t']$,
 (z, r, A) is a ρ -Moore box for g_s .

Solution : try $M(\square g_T, \square Jg_T, z, r, A, \rho)$,
where $T = [t, t']$.

Thickening with a predictor



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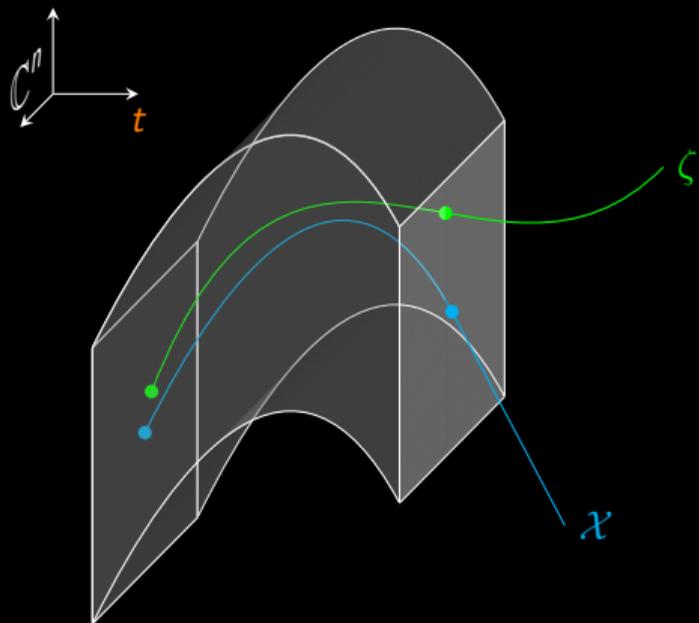
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Certifying the prediction

Problem : check that for all $s \in [t, t']$,
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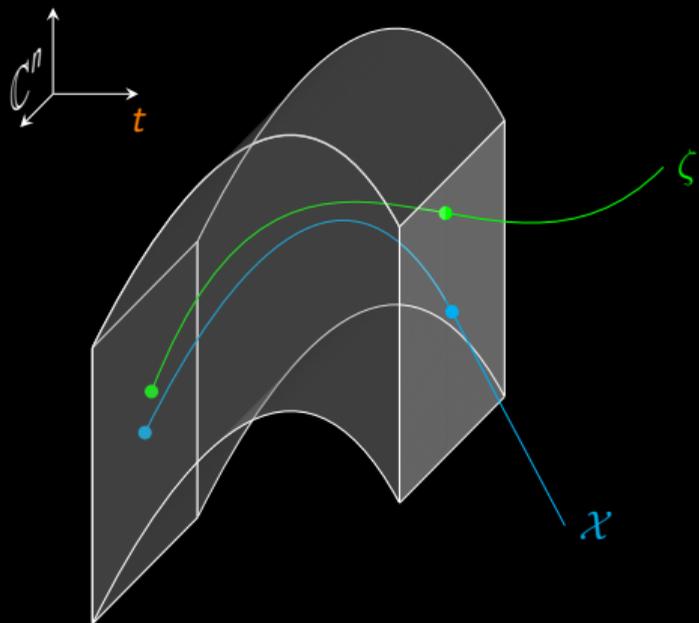
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where $T = [t, t']$.

This is too strong !

Thickening with a predictor



Predictor

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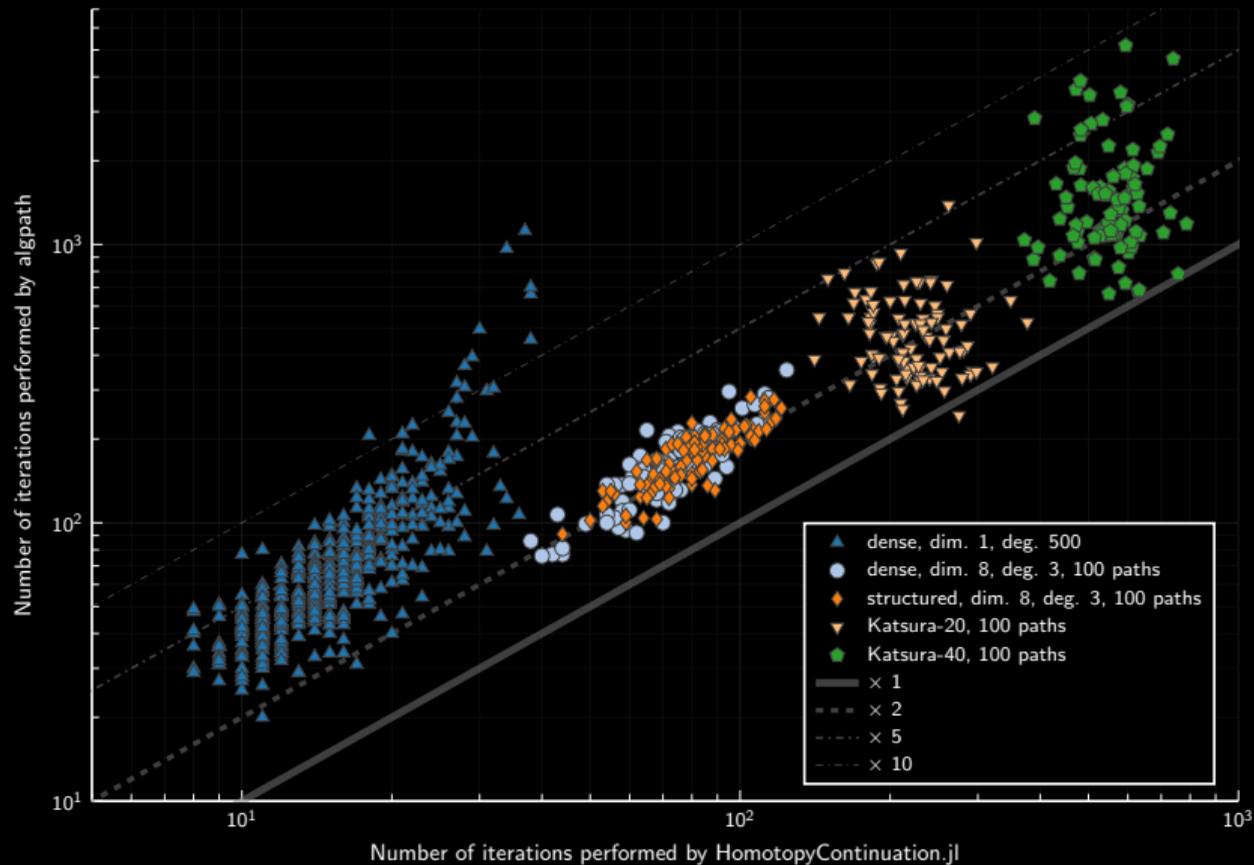
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Solution : compute

$$-Ag_s(\mathcal{X}(s)) + [I_n - A \cdot Jg_s(\mathcal{X}(s)) + B_r]B_r$$

using Taylor models on T .

Implementation and benchmarks



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Test data

We tested systems of the form $g_t(z) = tf^{\ominus}(z) + (1-t)f^{\triangleright}(z)$ (f^{\triangleright} is the start system, f^{\ominus} is the target system).

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Target systems

- Dense : f_i^\ominus 's of given degree with random coefficients
- Structured : f_i^\ominus 's of the form $\pm 1 + \sum_{i=1}^5 \left(\sum_{j=1}^n a_{i,j} z_j \right)^d$, $a_{i,j} \in_R \{-1, 0, 1\}$
- Katsura family (sparse - high dimension - low degree)

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Start systems

- Total degree homotopies : f_i^\triangleright 's of the form $\gamma_i(z_i^{d_i} - 1)$, $\gamma_i \in_R \mathbb{C}$, $d_i = \deg f_i^\ominus$
- Newton homotopies : $f^\triangleright(z) = f^\ominus(z) - f^\ominus(z_0)$

Benchmarks table

name	dim.	max deg	HomotopyContinuation.jl			algpah			Macaulay2		
			med.	ksteps/s	time (s)	med.	ksteps/s	time (s)	med.	ksteps/s	time (s)
dense	1	10	6	29	1.8	11	55	< 0.1	629	49	0.2
dense	1	30	10	43	1.9	23	25	< 0.1	830 k	28	19 min
dense	1	50	12	38	1.8	30	13	0.7		> 1 h	
dense	2	10	22	33	2.4	53	9.2	0.7	33 k	27	165
dense	2	30	24	5.8	6.4	85	1.4	72		> 1 h	
dense	2	50	27	2.3	32	117	0.53	12 min		> 1 h	
katsura *	11	2	112	38	4.4	199	6.0	3.5	20 k	11	203
katsura *	21	2	222	13	6.0	461	1.3	37		> 1 h	
katsura *	41	2	554	2.8	24	1371	0.19	13 min		> 1 h	
dense *	8	3	73	2.1	6.2	157	0.86	19	21 k	8.3	281
structured *	8	3	81	40	3.9	182	7.9	2.3	36 k	9.9	371
structured ^N	10	10	53	0.19	3.0	123	4.9	< 0.1		> 1 h	
structured ^N	20	20		> 8 GB		1591	1.2	1.5		> 8 GB	
structured ^N	30	30		> 8 GB		1989	0.43	5.2		> 8 GB	